

# MATH 565: Lecture 8 (02/05/2026)

Today: \* SGD for SVM  
\* Logistic regression loss  
\* coordinate descent (CD)

Recall

$$\nabla J_{\text{H-SVM}} = -y_i \bar{x}_i \delta(1 - y_i(\bar{w}^T \bar{x}_i) > 0) + \lambda \bar{w} \quad (\text{Hinge-SVM})$$

$$\nabla J_{L_2\text{-SVM}} = -y_i \bar{x}_i \max\{0, 1 - y_i(\bar{w}^T \bar{x}_i)\} + \lambda \bar{w} \quad (L_2\text{-SVM})$$

## SGD for H-SVM

$$\bar{w} \leftarrow \bar{w} (1 - \alpha \lambda) + \alpha \sum_{i \in S} y_i \bar{x}_i \delta(1 - y_i(\bar{w}^T \bar{x}_i) > 0)$$

Let  $S^+ = \{i \in S \mid y_i(\bar{w}^T \bar{x}_i) < 1\}$   $\rightarrow$  subset of indices in  $S$  for which  $\delta(\cdot) = 1$  above

$y_i(\bar{w}^T \bar{x}_i) < 0 \Rightarrow i$ : misclassified point/instance

$y_i(\bar{w}^T \bar{x}_i) \in (0, 1) \Rightarrow i$ : correctly classified instance, but lies close to decision boundary.

When  $y_i(\bar{w}^T \bar{x}_i) \geq 1$ ,  $i$  is correctly classified and well-separated  $\Rightarrow$  does not contribute to  $J$ .

## SGD for Hinge-SVM

$$\bar{w} \leftarrow \bar{w} (1 - \alpha \lambda) + \sum_{i \in S^+} \alpha y_i \bar{x}_i \quad \rightarrow \text{primal SVM algorithm}$$

proposed by Hinton in 1989!

$\rightarrow$  before VC dimension and other details were proposed by Vapnik and coauthors later on...

# Logistic Regression Loss

Note that the hinge loss function, while convex, is not smooth — there is a sharp "hinge" at the value of 1 (hence the name). The logistic regression loss can be considered as a smooth version of the hinge loss.

$$J_{LR} = \sum_{i=1}^n \log(1 + e^{-y_i(\bar{w}^T x_i)}) + \frac{1}{2} \|\bar{w}\|^2$$

Consider  $L(z) = \log(1 + e^{-z})$  with  $z = yf(\bar{x})$  as the prediction

$$= \log(e^{-z}(1 + e^z))$$

$$= -z + \log(1 + e^z)$$

→ 0 as  $z \rightarrow -\infty$

e.g.,  $z_i = y_i(\bar{w}^T x_i)$   
largely misclassified instances give huge negative values

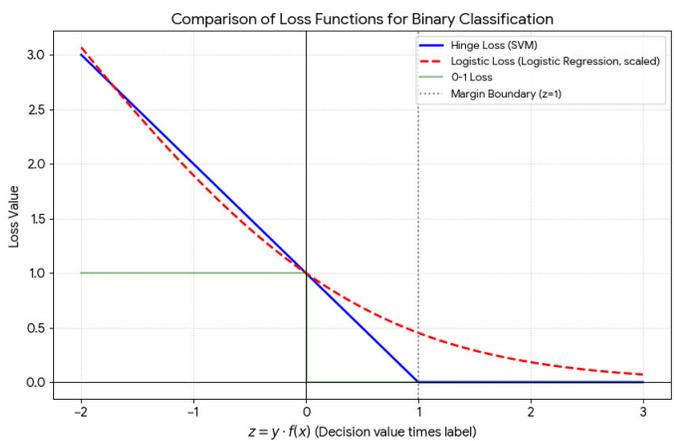
⇒ For largely misclassified instances,  $J_{LR}$  increases linearly as  $|\bar{w}^T x_i|$  increases. For such instances

recall that the hinge loss function is  $1 - z$  for  $z < 1$ ...

$$J_{H-SUM} - J_{LR} \approx 1$$

⇒ H-SUM and LR-SVM treat grossly misclassified instances similarly.

But  $J_{LR} > 0$  (ignoring  $\|\bar{w}\|^2$  term) for all instances.



$J_{LR}$  is differentiable while  $J_{H-SUM}$  is not.

(8-3)

In fact, the fit term in the  $J_{LR}$  loss function turns out to be strictly convex (on its own)!

Lemma 8  $J_{LR}$  without the  $\frac{1}{2}\|\bar{w}\|^2$  regularizer term is strictly convex.

But we usually add  $\frac{1}{2}\|\bar{w}\|^2$  still, as this extra term encourages sparsity. We could instead use  $\sum_{i=1}^n |w_i|$  as an  $L_1$ -regularity term. But then again,  $|w_i|$  is not smooth either...

We finish with the details of gradient descent using the logistic regression loss function for SVM.

$$\nabla J_{LR} = - \sum_{i=1}^n \frac{y_i \bar{x}_i}{[1 + e^{-y_i(\bar{w}^T \bar{x}_i)}]} + \lambda \bar{w}$$

Hence, the SGD update  $\bar{w}$  is given as follows.

$$\bar{w} \leftarrow \bar{w} (1 - \alpha \lambda) + \sum_{i \in S} \frac{\alpha y_i \bar{x}_i}{[1 + e^{-y_i(\bar{w}^T \bar{x}_i)}]}$$

# Coordinate Descent (CD)

Recall the gradient descent update:  $\bar{w} \leftarrow \bar{w} - \alpha \nabla J$ .

In coordinate descent (CD), we optimize one coordinate at a time.

$$\bar{w} = \underset{\bar{w}}{\operatorname{argmin}} \{ J(\bar{w}) \mid \text{only } w_i \text{ varies} \}$$

- \* only one variable to handle — can be (much) easier.
- \* can use line search if not able to solve exactly.

Cycle through all  $i=1, \dots, d$ .  
 if no  $w_i$  changes, STOP. → in a full cycle

\* If  $J$  is convex and differentiable, then the converged solution is optimal.

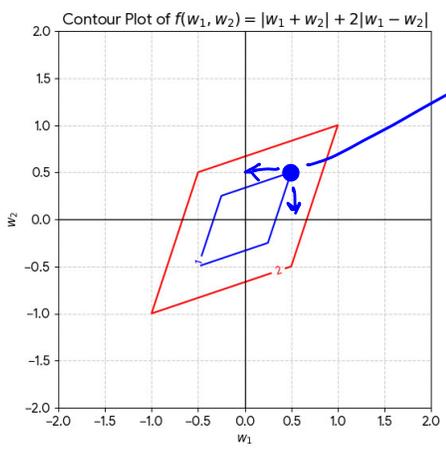
\* But if  $J$  is not differentiable, this guarantee does not hold, even when it may be convex.

Consider  $J(\bar{w}) = (w_1 + w_2) + \alpha |w_1 - w_2|$ ,  $\alpha > 1$ . } can show that  $J$  is convex.

$J$  is minimal at  $(0,0)$ .

But if we're at  $(1,1)$ , neither coordinate will decrease  $J$ .

two contours of  $J=1, J=2$ .



Still, we can give a characterization of a fairly general class of loss functions on which CD is well-behaved. (8-5)

Lemma 9 Let  $J(\bar{w}) = G(\bar{w}) + \sum_{i=1}^d H_i(w_i)$  where  $G(\bar{w})$  is convex and differentiable, while  $H_i(w_i)$  are convex but may not be differentiable. Then, CD converges to the global minimum of  $J$ .

The  $L_1$ -regularizer has this structure:  $H_i = |w_i|$ , giving  $\sum_{i=1}^d |w_i|$  as the regularizer term.

But in some cases, variable transformations can help even if  $J$  is not in this form.

e.g.,  $J(\bar{w}) = G(\bar{w}) + |w_1 + w_2| + \alpha |w_1 - w_2|$ ,  $\alpha > 1$ . Here,  
 $\rightarrow$  convex, differentiable

we can use  $u_1 = \frac{w_1 + w_2}{2}$  and  $u_2 = \frac{w_1 - w_2}{2}$  to get  
 $w_1 = u_1 + u_2$  and  $w_2 = u_1 - u_2$ , giving

$$J(\bar{u}) = G(u_1 + u_2, u_1 - u_2) + 2|u_1| + 2\alpha|u_2|,$$

which has structure specified in Lemma 9.

$\rightarrow$  CD will work well on this version of  $J$ .

# Linear Regression with Coordinate Descent

To understand CD better, we apply it to linear regression (without regularization)

$$J(\bar{w}) = \frac{1}{2} \|D\bar{w} - \bar{y}\|^2 = \frac{1}{2} \sum_{i=1}^n (\bar{w}^T x_i - y_i)^2$$

$$= \frac{1}{2} \sum_{i=1}^n \left( \sum_{j=1}^d w_j x_{ij} - y_i \right)^2$$

we consider CD for  $w_k$

$\underbrace{\hspace{10em}}_{\rightarrow w_k x_{ik} + \sum_{j \neq k} w_j x_{ij} - y_i}$

$$\frac{\partial J}{\partial w_k} = \sum_{i=1}^n (w_k x_{ik} + \sum_{j \neq k} w_j x_{ij} - y_i) x_{ik} = 0$$

first order optimality

$$\Rightarrow w_k = \frac{-\sum_{i=1}^n (\sum_{j \neq k} w_j x_{ij} - y_i) x_{ik}}{\sum_{i=1}^n x_{ik}^2}$$

term not included

With  $\bar{r} = \bar{y} - D^T \bar{w} = \bar{y} - \sum_{j \neq k} \bar{d}_j w_j - w_k \bar{d}_k$   $\bar{d}_j$ :  $j^{\text{th}}$  column of  $D$ .

↳ vector of residuals

The update step is given as follows.

$$w_k^{\text{new}} = \frac{\bar{d}_k^T (\bar{r} + w_k^{\text{old}} \bar{d}_k)}{\|\bar{d}_k\|^2}$$

$$D = \begin{bmatrix} 1 & 2 & \dots & k & \dots & d \\ x_{11} & x_{12} & \dots & x_{1k} & \dots & x_{1d} \\ x_{21} & x_{22} & \dots & x_{2k} & \dots & x_{2d} \\ \vdots & \vdots & & \vdots & & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nk} & \dots & x_{nd} \end{bmatrix}$$

$$= w_k^{\text{old}} + \frac{\bar{d}_k^T \bar{r}}{\|\bar{d}_k\|^2}$$

we assume the trivial case of  $\bar{d}_k = \bar{0}$  does not occur.

If data columns are normalized,  $\|\bar{d}_k\|^2 = 1$ , and we get  $w_k^{\text{new}} = w_k^{\text{old}} + \bar{d}_k^T \bar{r}$ .

More generally, we update

$$w_k^{\text{new}} \leftarrow w_k^{\text{old}} + \bar{d}_k^T \bar{r} \rightarrow \text{extremely efficient!}$$

We also update the residuals  $\bar{r}$  as follows:

$$\bar{r} \leftarrow \bar{r} - \bar{d}_k (\Delta w_k) \rightarrow w_k^{\text{new}} - w_k^{\text{old}}$$