Lattices and Integer Optimization -A Tutorial (Part II)

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- lattice-based approaches to number partitioning in hard phase (joint work with Bill Webb, Nathan Moyer (WSU))

Integer Programming (IP)

• IP feasibility

Given

$$P = \{ \mathbf{x} | \boldsymbol{\ell} \leq A\mathbf{x} \leq \mathbf{b} \},\$$

Find $\mathbf{x} \in P \cap \mathbb{Z}^n$, or prove that no such \mathbf{x} exists.

Given polyhedron P, integral vector \mathbf{c} ,

• width(\mathbf{c}, P) = max { $\mathbf{c}^T \mathbf{x} | \mathbf{x} \in P$ } - min { $\mathbf{c}^T \mathbf{x} | \mathbf{x} \in P$ } = $\gamma - \delta$.

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- no branches created $\Rightarrow P$ has no integral point
- when $\mathbf{c} = \mathbf{e}_i$, we are branching on single variable x_i
- different choices of c produce very different effects on branching

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- a "primal" method

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 Was not tried. Going to nullspace has some benefits (esp. in cryptography applications)
- both CBR-R and CBR-N actually work for essentially all hard IPs used to test "non-traditional" IP algorithms

t + 1-level decomposable knapsack problems

• $\mathbf{a} = \mathbf{p}_1 M_1 + \mathbf{p}_2 M_2 + \dots + \mathbf{p}_t M_t + \mathbf{r}$, with $M_1 > M_2 > \dots > M_t$ and for suitable β, δ

 $(KP) \quad \beta \leq \mathbf{a} \, \mathbf{x} \leq \beta + \delta, \quad \mathbf{0} \leq \mathbf{x} \leq \mathbf{u}, \quad \mathbf{x} \in \mathbb{Z}^n$

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- with suitably chosen data, the problem is "both hard and easy"
- if t = 1, we just write $\mathbf{p} = \mathbf{p}_1$, $M = M_1$

DKP instances for t = 1

• a classic example: Jeroslow's problem

$$2(x_1 + \dots + x_n) = n x_i \in \{0, 1\}^n$$

where n is odd.

- with B&B branching on the x_i , no node is pruned above level n/2
- if we branch on $x_1 + \cdots + x_n$, we solve it at the root node
- here p = 1, r = 0, M = 2

Other known instances for t = 1

- p = 1, r = (2⁰,..., 2ⁿ⁻¹), u = 1, M = 2^{n+ℓ+1} : Todd's problem from Chvátal "Hard knapsack problems" (1980)
- p = 1, r = (1,...,n), u = 1, M = n(n+1): Avis' problem from same paper
- Gu, Nemhauser, Savelsbergh (2001) modification of Todd's problem
- \bullet Cornuéjols, Urbaniak, Weismantel, Wolsey (1996): $\mathbf{p}>\mathbf{0},\,\mathbf{u}=+\infty$ (inequality)
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- $\mathbf{p} = \mathbf{1}$, $\mathbf{r} = (1, \dots, n)$, $\mathbf{u} = \mathbf{1}$, M = n(n+1): Avis' problem from same paper
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All, except the last two take $\geq 2^{n/2}$ nodes for ordinary B&B. In last, \exists a large rhs for which the problem is infeasible

Recipe for DKPs and hardness

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• lower bound on the number of nodes necessary for *ordinary* B&B (using x_j 's)

DKPs get harder as t grows

two infeasible knapsack problems: can you tell which one is harder?

 $\begin{aligned} 1473x_1 + 1524x_2 + 1569x_3 + 1570x_4 + 1575x_5 + 1624x_6 + 1625x_7 \\ + 2160x_8 + 2206x_9 + 2207x_{10} + 2211x_{11} + 2211x_{12} + 2257x_{13} \\ + 2260x_{14} + 2305x_{15} + 2843x_{16} + 2943x_{17} + 2947x_{18} + 2991x_{19} \\ + 2993x_{20} + 2997x_{21} + 3528x_{22} + 3577x_{23} + 3631x_{24} + 3677x_{25} \\ &= 28980, \ x_i \in \{0, 1\}. \end{aligned}$

 $\begin{aligned} 1314x_1 + 1315x_2 + 1317x_3 + 1318x_4 + 1971x_5 + 1972x_6 + 1973x_7 \\ + 1976x_8 + 1977x_9 + 1977x_{10} + 2629x_{11} + 2630x_{12} + 2631x_{13} \\ + 2631x_{14} + 2633x_{15} + 2634x_{16} + 2635x_{17} + 2635x_{18} + 3287x_{19} \\ + 3287x_{20} + 3287x_{21} + 3289x_{22} + 3292x_{23} + 3293x_{24} + 3293x_{25} \\ &= 28981, \ x_i \in \{0, 1\}. \end{aligned}$

Similar looking DKPs

- The second one has t = 1, and takes $\approx 22,000$ nodes to prove infeasibility.
- The first one has t = 2, and takes ≈ 3.6 million nodes to prove infeasibility. (Note that $2^{25} \approx 33$ million).

DKPs get more interesting as t **grows**

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width(p₁, Q) > 1, but [max{p₁x : x ∈ Q} - min{p₁x : x ∈ Q}] only contains one integer. So "branching" on p₁x means adding p₁x = k to the LP for some k

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- a "not thin" direction beats a thin direction!

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- if we fix $\mathbf{p}_i^T \mathbf{x}$, the problem simplifies ($\mathbf{p}_i M_i$ disappears)
- width in direction of $\mathbf{p}_{s+1}\mathbf{x}$, after we branched on $\mathbf{p}_1\mathbf{x},\ldots,\mathbf{p}_s\mathbf{x}$ is

$$O\left(\frac{rhs}{M_{s+1}^2} + \frac{\delta}{M_{s+1}}\right).$$

• Briefly: the "good reasons" for $p_i x$ are transferred to the variable y_{n-i} in the reformulation

Example of CBR of a DKP



Hard for branching on x_i s. Easy for branching on $x_1 + x_2$: max = 5.94, min = 5.04.

Lattices and Integer Optimization

After Reformulation ...



 \dots branching on y_2 proves infeasibility!

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• Theorem: If separation between $M_1 > M_2 > \cdots > M_t$ is suitably large, then

$$\begin{pmatrix} \mathbf{p}_1 \\ \mathbf{p}_2 \\ \vdots \\ \mathbf{p}_t \end{pmatrix} U = \begin{pmatrix} 0 & 0 \dots & 0 & 0 & 0 & * \\ 0 & 0 \dots & 0 & 0 & * & * \\ \vdots & & & & & \\ 0 & 0 \dots & * & \dots & * & * \end{pmatrix}$$

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When computing U, we do not know the decomposition!

• using the correspondence $U\mathbf{y} = \mathbf{x}$, we get

$$\mathbf{p}_1 \mathbf{x} = \mathbf{p}_1(U\mathbf{y}) = (\mathbf{p}_1 U)\mathbf{y} = (\mathbf{p}_1 U)_n y_n.$$

• Corollary:

- Branching on y_n in reformulation \Leftrightarrow branching on $\mathbf{p}_1 \mathbf{x}$ in original problem
- Afterwards: $y_{n-1} \Leftrightarrow \mathbf{p}_2 \mathbf{x}$, etc.
- Analogous result for CBR-N

Summary of CBR

- general reformulation technique for arbitrary IPs.
- has two variants: CBR-R and CBR-N, both work in practice and can be analyzed
- a fairly general class of IPs provably hard for ordinary B&B
- the provably hard problems turn into provably easy ones: the reformulation "uncovers" the hidden, dominant directions
- The *cascade* problems: thinner \neq better!

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- The *cascade* problems: thinner \neq better!
- Pataki et al. (2010) B&B solves "almost all" instances of CBR-R of {x | ℓ₁ ≤ Ax ≤ u₁; ℓ₂ ≤ x ≤ u₂} at root node if A_{ij} ∈ U{1,...,M} for sufficiently large M

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- allocate $\beta = 1/2 \alpha$, or, as close as possible to β , to each subset

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- balanced NPP (BALNPP): $|S_1| = |S_2| = n/2$ (for even n)

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NPP – Example

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 - both subset sums = 15; $\triangle = \triangle^* = 0$
- $\triangle^* = 0$ (or $\triangle^* = 1$ when α odd) gives a *perfect* partition

• practical

• theoretical

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- scheduling jobs on processors (NPP into $k \ge 3$ subsets: multiprocessor scheduling problem)
- VLSI circuit design
- public key cryptography
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 - phase transition (fully characterized mathematically)
 - NP-completeness of other problems involving numbers bin packing, knapsack etc.

• $a_j = U[1, R]$ for $R \in \mathbb{Z}_{>0}$

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* Karmarkar, Karp, Lueker, Odlyzko (88): median \triangle^* for NPP

- * Lueker (98): average \triangle^* for NPP
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Phase transition of NPP and \mathsf{BALNPP}

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recall, $\triangle^* = O(\sqrt{n} 2^{-n} R)$

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- typical numbers are *huge*; for n = 30, look at a_j 's with 11 digits!

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Theorem 1. DNPP_d is reducible to DCVP for d > 0.

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- generalization of Micciancio (2001) reduction of subset sum to CVP

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- Lagarias & Odlyzko (85), Coster et al. (92): for subset sums



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• write NPP MIP as $\min\{w \mid A\mathbf{x} + Bw \leq \mathbf{b}, \mathbf{x} \in \mathbb{Z}^n\}$ with

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- running times increase with ${\boldsymbol R}$
- for $n \ge 100$, KK may still be the best (current) option

Outline

- Number Partitioning Problem (NPP)
- Karmarkar-Karp differencing (KK)
- NPP and the Closest Vector Problem (CVP)
- \bullet A Basis Reduction Heuristic for NPP
- Mixed Integer Program (MIP) for NPP